Abstract—In this paper, we investigate the energy harvesting (EH) technique and accordingly design transceivers for a $K$ link multiple-input multiple-output (MIMO) interference channel. Each link consists of two full-duplex (FD) internet of things (IoT) nodes exchanging information simultaneously in a bi-directional communication channel. All the nodes suffer from interference, in particular strong self-interference and inter-node interference, due to operating in FD mode and simultaneous transmission at each link, respectively. Further, we divide the received signal at each node into two parts. While one part of the signal is used for information decoding, the other part is used for EH. We jointly design the transmit and receive beamforming vectors and receiver power splitting ratios by minimizing the total transmission power of the system, subject to both signal-to-interference-plus-noise ratio (SINR) and EH threshold constraints. Furthermore, the case of multiple-input single-output (MISO) interference channel is also included for the sake of comparison. We also revisit the above problems for the case when the available channel state information (CSI) at the transceiver is imperfect, where the errors of the CSI are assumed to be norm bounded. Simulation results show that the EH technique can harvest enough energy to support power consumption limited IoT devices by aiding in recharging their respective batteries.

Index Terms—Beamforming, energy harvesting, full-duplex, MIMO interference channels, power splitting, self-interference.

I. INTRODUCTION

Wireless data traffic has exponentially increased over the last decade and it is projected to increase even further. As a result, effective and efficient utilization of the scarce spectrum resources has become an extremely important issue. The currently deployed half-duplex (HD) wireless communication systems do not utilize the spectrum efficiently as transmission and reception happen orthogonally, either in time, denoted as time division duplexing (TDD), or in frequency, denoted as frequency division duplexing (FDD). Among the emerging technologies for next-generation wireless networks, full-duplex (FD) communication is considered as a way to potentially double the capacity of wireless communications. Simultaneous transmission and reception of overlapping signals in the same frequency had generally been assumed impossible in wireless communications due to the challenges involved in handling the self-interference [1], which is caused due to the signal received at the receive antennas of a FD node from its own transmitter antennas. However, thanks to the recent progress of cancellation made on self-interference suppression, FD communication systems have triggered enormous research interests [2], [3]. Consequently, FD is being considered as a key enabling technique for 5G and beyond systems [4], since it enables available spectral resources to be fully utilized in both time and frequency.

A single-antenna FD system was investigated in [5], while in [6], a multiple-antenna FD system was studied. Many feasible solutions including antenna, analog and digital cancellation have been demonstrated experimentally to mitigate the overwhelming self-interference, which is the fundamental challenge in implementing a full-duplex radio [7]–[10]. However, due to imperfect self-interference channel knowledge and hardware impairments in the transmitter chain, the self-interference cannot be completely eradicated in practice. In this case, the performance is limited by the residual self-interference, which is induced by the imperfection of the transmit and receive front-end chain [11]–[19]. In addition to self-interference, co-channel interference (CCI) from uplink to downlink (UL) nodes is another challenge in FD networks that needs to be overcome to fully exploit the multi-access nature of the wireless medium in conjunction with FD systems. To optimize the system performance, self-interference and CCI in FD systems should be addressed jointly through beamforming [15], [20], [21].

It is a common practice in wireless communication devices...
that energy is supplied to an energy constrained wireless device with the help of rechargeable or replaceable batteries. However, these batteries have limited operation time and they need to be replaced or recharged frequently. Not only is this inconvenient, but also usually incurs high costs. According to the analyses in literature and the fact that radio signals can potentially carry wireless information and energy simultaneously, a new promising solution, energy harvesting (EH) through simultaneous wireless information and power transfer (SWIPT), has been proposed [22]–[24]. This is seen as a key enabling technique for next generation wireless devices. In particular, the recent advent of low powered internet of things (IoT) devices and device to device (D2D) communications has made EH an interesting proposition. Such IoT/D2D devices will mainly make use of the current state of the art technologies such as bluetooth 5.0 low energy (LE), IEEE 802.11n, IEEE 802.11ac, etc., along with other future communication technologies such as mmWave transmission. The emergence of these low power consumption technologies makes it possible to realize wireless power transfer, which can act as a cornerstone for future green communications. This EH technique can be realized by two practical means, namely time-switching (TS) and power splitting (PS) which were introduced in [25]. The single-input single-output (SISO) system with additive white Gaussian noise (AWGN) was considered in [26], where a capacity-energy function to characterize the fundamental trade-off between wireless information and energy transmission was proposed. Moreover, SWIPT for multiple-antenna systems was studied in [27].

Further from a market perspective (Global Market Forecast (GMF) upto 2023), the EH system market by technology (light, vibration, RF, thermal), component, application (building and home automation, consumer electronics, IoT, industrial, transportation, security) is expected to witness a growth from USD 311.2M in 2016 to USD 645.8M by 2023, at a CAGR of 10.62% between 2017 and 2023. The key players in this market are EnOcean GmbH (Germany), Mide Technology Corporation (US), Lord Microstrain (US); secondary battery and capacitor providers such as Cymbet Corporation (US), Linear Technologies (US), Murata Manufacturing Co. Ltd., (Japan), and Infinite Power Solution Inc. (US); power management IC manufacturers such as Linear Technologies (US), Cypress Semiconductor Corp. (US), STMicroelectronics (Switzerland), Texas Instruments (US), and Fujitsu (Japan).

Motivated by the potential of FD and EH in future wireless communication systems, such as IoT/D2D, in this paper we investigate the EH potential of multiple-input multiple-output (MIMO) interference channels consisting of $K$ pairs of IoT/D2D FD nodes with SWIPT. The consideration of interference channel is suitable for IoT/D2D devices as multiple low powered devices will interact among each other in an IoT/D2D communication scenario. Each IoT/D2D node is assumed to have $N^T$ transmit and $M^a$ receive antennas, where $i \in \{1, 2, ..., K\}$ and $a \in \{1, 2\}$ and operates in FD mode. The consideration of FD and EH techniques at each node allows all the participating nodes to transmit/receive signal and harvest energy simultaneously. The harvested energy can then be used by the nodes to recharge their batteries without the need for external power supply.

Indeed, the studied system in our paper shares many similarities to the traditional interference channel networks, both in terms of the system concept, service requirements, as well as the design guidelines. Nevertheless, the application of FD technology for EH in a IoT/D2D network introduces new fundamental challenges to the traditional interference channel models, which is the main focus of this paper. The main distinctions are summarized as follows:

- The EH requirements of an IoT network need to be revised when operating in a FD mode. This is because in a FD interference channel network, all the nodes share the same channel resource for transmission and reception, which results in the imposition of a higher interference intensity on the network. This issue becomes more critical considering the fact that the acquisition of an accurate CSI regarding the interference paths from the multiple users is relatively unrealistic, and calls for the consideration of a joint robust transmission strategy.
- In an FD MIMO interference channel network, the self-interference at each node is a critical challenge, and strongly relates the performance/design of the UL/DL reception to the DL/UL transmission. In this respect, the consideration of an accurate transceiver model, including the impacts of transmission and reception distortions are critical, as it is well-established in the context of FD system design and analysis.
- In an FD MIMO interference channel network, apart from the self-interference, the interference paths among all nodes should be additionally taken into account. This impacts both the system performance, as well as the design strategy.

Note that the aforementioned considerations regarding the design of a robust FD multi-node MIMO IoT network, result in a relatively complicated problem structure. For perfect channel state information (CSI) at the nodes, the optimization problem is defined according to the SINR and EH constraints, which results in a non-convex optimization problem. When the CSI availability at the transmitters is imperfect, the errors of the CSI are assumed to be norm bounded, resulting in a semi-infinite problem.

Moreover, due to the transmit and receive distortions at the FD nodes in addition to imperfect CSI, EH and SINR become complicated functions, which make the transformation of the constraints in the optimization problems complicated. This, in turn, calls for a rigorous optimization and analysis, together with a dedicated computational complexity study. Numerical results demonstrate the feasibility of EH for FD. It is shown that the harvested energy can support small IoT devices with minimal power requirements to recharge their batteries.

**Notations:** The following notations are used in this paper. Matrices and vectors are denoted as bold capital and lowercase letters, respectively. $(\cdot)^T$ is the transpose, $(\cdot)^H$ represents the conjugate transpose, and $(\cdot)^*$ the conjugate. $\mathbb{E}\{\cdot\}$ denotes

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1This paper does not focus on the modeling of charging of the battery. Analysis of the battery dynamics is beyond the scope of this paper. Interested readers can refer to [28], [29] for details on battery modelling.
the statistical expectation and diag(A) is the diagonal matrix with the same diagonal elements as A. \(I_N\) is the N by N identity matrix, and \(\text{tr}\{\cdot\}\) is the trace operator. \(CN(\mu, \sigma^2)\) denotes a complex Gaussian distribution with mean \(\mu\) and variance \(\sigma^2\). \(\mathbb{C}^{N \times M}\) denotes the set of complex matrices with a dimension of \(N\) by \(M\). \(|\cdot|\) and \(||\cdot||\) denote the absolute value and the Euclidean norm, respectively. The operator for \(N\) variance is denoted as \(\sigma^2\).

The node \(i\) receives signals from all the transmitters in the system. \(M\) and \(N\) denotes the number of MIMO FD IoT nodes in the system communication. For simplification, we assume that the \(N\times 1\) signal vector transmitted by node \(i\) is given by
\[
x_i^{(a)} = v_i^{(a)} d_i^{(a)}, \quad i = 1, \ldots, K, \quad a \in \{1, 2\},
\]
where \(v_i^{(a)} \in \mathbb{C}^{N\times 1}\) represents the precoding vector.

The received signal at node \(i\) is a combination of the signals transmitted by all the IoT nodes plus the additive noise, which is written as
\[
y_i^{(a)} = \left(h_{ii}^{(ab)}\right)^H (x_i^{(b)} + c_i^{(b)}) + \left(h_{ii}^{(aa)}\right)^H (x_i^{(a)} + c_i^{(a)}) + \sum_{j \neq i}^{K} \sum_{c = 1}^{2} \left(h_{ij}^{(ac)}\right)^H (x_j^{(c)} + c_j^{(c)}) + e_i^{(a)} + n_i^{(a)}, \quad i = 1, \ldots, K, \quad (a, b) \in \{1, 2\}, \quad a \neq b. \quad (2)
\]

Here, \(n_i^{(a)}\) is the additive white Gaussian noise (AWGN) at node \(i\) with zero mean and variance \(\sigma_n^2\).

In (2), \(e_i^{(a)} \in \mathbb{C}^{N\times 1}, \quad i = 1, \ldots, K, \quad a \in \{1, 2\}\) is the noise at the transmitter antennas of node \(i\), which models the effect of limited transmitter dynamic range (DR) and closely approximates the effects of additive power-amplifier noise, non-linearities in the DAC and phase noise [12]. The mean of \(c_i^{(a)}\) is 0, and the variance of \(c_i^{(a)}\) is proportional to the energy of the intended signal at each transmit antenna, i.e.,
\[
c_i^{(a)} \sim CN(0, \kappa \text{diag}(v_i^{(a)} (v_i^{(a)})^H)), \quad c_i^{(a)} \perp x_i^{(a)}, \quad (3)
\]
where \(\perp\) denotes the statistical independence.

In (2), \(e_i^{(a)}\) is the additive distortion at the receiver antenna of node \(i\), which models the effect of limited receiver DR and closely approximates the combined effects of additive gain-control noise, non-linearities in the ADC and phase noise. The mean of \(e_i^{(a)}\) is 0 and the variance is proportional to the energy of the undistorted received signal at the receive antenna. In particular, \(e_i^{(a)}\) is modeled as
\[
e_i^{(a)} \sim CN(0, \kappa \Phi_i^{(a)}), \quad e_i^{(a)} \perp u_i^{(a)}, \quad (4)
\]
where \(\Phi_i^{(a)} = \text{Var}(u_i^{(a)})\) is the variance of \(u_i^{(a)}\), and \(u_i^{(a)}\) is the undistorted received signal at the node \(i\), i.e., \(u_i^{(a)} = y_i^{(a)} - e_i^{(a)}\).

The consideration of both the MISO and MIMO cases is due to the fact that the MIMO case requires certain approximations to derive the covariance matrix of the signal. However, the MISO case doesn’t require any such approximations and hence the MISO case may not be a straightforward extension of the MIMO case in our analysis.

III. FULL DUPLEX SYSTEMS WITH PERFECT CSI

In this section, we assume that perfect CSI is available at all the IoT nodes. The MISO scenario will be investigated first followed by the MIMO case.2

A. Transceiver design for MISO interference channel

The transmitted data stream of node \(i\) is denoted as \(d_i^{(a)}, \quad i \in \{1, \ldots, K\}, \quad a \in \{1, 2\}\), and is assumed to be complex, zero mean, independent and identically distributed (i.i.d.) with unit variance. The \(N\times 1\) signal vector transmitted by node \(i\) is given by
\[
x_i^{(a)} = v_i^{(a)} d_i^{(a)}, \quad i = 1, \ldots, K, \quad a \in \{1, 2\}, \quad (1)
\]
Node $i^{(a)}$ has the knowledge of the interfering codewords $x_i^{(a)}$ and the channel $h_{ii}^{(aa)}$. So the self-interference term $(h_{ii}^{(aa)})^T x_i^{(a)}$ is known, and thus can be canceled [12]. The received signal after self-interference cancellation can then be written as

$$y_i^{(a)} = g_i^{(a)} - (h_{ii}^{(aa)})^T x_i^{(a)}$$

where $v_i^{(a)}$ is the unknown interference-plus noise component after self-interference cancellation, and is given by

$$v_i^{(a)} = (h_{ii}^{(ab)})^T c_i^{(b)} + (h_{ii}^{(aa)})^T c_i^{(a)} + e_i^{(a)} + n_i^{(a)}$$

$$+ \sum_{j \neq i}^K \sum_{c=1}^2 (h_{ij}^{(ac)})^T (x_j^{(c)} + c_j^{(c)}).$$

Now, using (3)-(4), $\Sigma_i^{(a)}$, the variance of $v_i^{(a)}$ is given as (7).

By means of a power splitter, the received signal is now divided into two parts, one for the information decoder and another for EH. Let $\rho_i^{(a)}$ denote the PS ratio for receiver $i^{(a)}$, which means that a portion $\rho_i^{(a)}$ of the signal power is used for signal detection while the remaining portion $1-\rho_i^{(a)}$ is diverted to an energy harvester. Accordingly, the available signal for information decoding at receiver $i^{(a)}$ can be expressed as

$$r_i^{(a)} = \sqrt{\rho_i^{(a)}} y_i^{(a)} + m_i^{(a)},$$

where $m_i^{(a)}$ is the additional AWGN circuit noise with zero mean and variance $\sigma_i^{(a)}$ due to phase offset and non-linearities during baseband conversion [32]. Using (8), the SINR at receiver $i^{(a)}$ is given by

$$\text{SINR}_{i^{(a)}} = \frac{\rho_i^{(a)} \left| (h_{ii}^{(ab)})^T v_i^{(b)} \right|^2}{\rho_i^{(a)} \Sigma_i^{(a)} + \sigma_i^{(a)}^2}.$$  

Besides, the total harvested energy that can be stored by receiver $i^{(a)}$ is given as

$$\text{EH}_{i^{(a)}} = \xi_i^{(a)} (1 - \rho_i^{(a)}) \mathbb{E} \left\{ |y_i^{(a)}|^2 \right\}$$

$$= \xi_i^{(a)} (1 - \rho_i^{(a)}) \left| (h_{ii}^{(ab)})^T v_i^{(b)} \right|^2$$

$$+ \left| (h_{ii}^{(aa)})^T v_i^{(a)} \right|^2 + \Sigma_i^{(a)},$$

where $\xi_i^{(a)} \in (0, 1)$ denotes the energy conversion efficiency of the $i^{(a)}$th EH unit.

We focus on transmit filter and PS ratio design, in order to minimize the total transmitted power, subject to SINR and EH constraints. The optimization scheme is formulated as follows.

$$\min_{\rho_i^{(a)}, \mu_i^{(a)}} \sum_{i=1}^K \sum_{b=1}^2 \|v_i^{(b)}\|^2$$

s.t. $\text{SINR}_{i^{(a)}} \geq \gamma_i^{(a)}, \forall (i,a)$, $\text{EH}_{i^{(a)}} > \delta_i^{(a)}, 0 \leq \rho_i^{(a)} \leq 1, \forall (i,a), (11a)$

where $\gamma_i^{(a)}$ and $\delta_i^{(a)}$ are the SINR and EH thresholds at the $i^{(a)}$th IoT receiver, respectively. The EH constraint represents the minimum amount of energy required in order to ensure that sufficient amount of energy is harvested in each transmission time. To obtain the optimal solution, the sufficient conditions to obtain a feasible solution and the procedure and techniques will be discussed in the following sections.

B. Extension to MIMO Interference Channel

In this section, we extend the model proposed in the previous section to multiple-antenna IoT receivers, where the nodes at the $i^{th}$ link now have $M_i$ receive antennas. Note that the channel vectors $h_{ii}^{(ac)}, \forall (i,j,a,c)$ in the MISO case is now replaced with the channel matrices $H_{ij}^{(ac)}, \forall (i,j,a,c)$ for the MIMO case. Accordingly, for this case, the SINR$_i^{(a)}$ and EH$_i^{(a)}$ are defined as

$$\text{SINR}_{i^{(a)}} = \frac{\rho_i^{(a)} \left| (u_i^{(a)})^H H_{ii}^{(ab)} v_i^{(b)} \right|^2}{\rho_i^{(a)} \left| (u_i^{(a)})^H \Sigma_i^{(a)} u_i^{(a)} + \sigma_i^{(a)}^2 \right| \|u_i^{(a)}\|^2},$$

$$\text{EH}_{i^{(a)}} = \xi_i^{(a)} (1 - \rho_i^{(a)}) \text{tr} \left\{ H_{ii}^{(ab)} v_i^{(b)} (v_i^{(b)})^H (H_{ii}^{(ab)})^H \right\}$$

$$+ H_{ii}^{(aa)} v_i^{(a)} (v_i^{(a)})^H (H_{ii}^{(ac)})^H + \Sigma_i^{(a)}.$$

In (12) and (13), $\Sigma_i^{(a)}$ is the covariance matrix of the total interference-plus noise components, which is approximated by ignoring the terms that include $\kappa \beta \ll 1$, and is expressed as (14)

$^4$Note that approximation of $\Sigma_i^{(a)}$ is a practical assumption [12], as the terms $\kappa$ and $\beta$ are much smaller than 1.
Now, the optimization problem (11) can be reformulated for the MIMO case, as
\[
\min_{\mathbf{v}_i^{(b)}, \mathbf{u}_i^{(a)}, \rho_i^{(a)}} \quad \frac{1}{K} \sum_{i=1}^{K} \sum_{b=1}^{2} \left\| \mathbf{v}_i^{(b)} \right\|^2 \\
\text{s.t.} \quad \text{SINR}_i^{(a)} \geq \gamma_i^{(a)}, \quad \forall (i,a), \\
E \mathbf{H}_i^{(a)} \geq \sigma_i^{(a)}, \quad \forall (i,a), \\
0 \leq \rho_i^{(a)} \leq 1, \\
\left\| \mathbf{u}_i^{(a)} \right\|^2 = 1, \quad \forall (i,a), \\
\mathbf{W}_i^{(b)} \geq 0, \quad \forall (i,a), \\
\mathbf{W}_i^{(b)} \geq 0, \quad \forall (i,a),
\]  
where \( \mathbf{u}_i^{(a)} \in \mathbb{C}^{M_i \times 1}, i \in \{1, \ldots, K\}, a \in \{1,2\} \) is the linear receiver applied at the receiver \( i^{(a)} \).

Problem (15) is non-convex and difficult to solve due to the quadratic terms involving all transmit beamforming vectors. In order to solve this problem, we introduce a new variable \( \mathbf{W}_i^{(b)} \triangleq \mathbf{v}_i^{(b)} \left( \mathbf{v}_i^{(b)} \right)^{H}, \forall (i,b) \) with rank(\( \mathbf{W}_i^{(b)} \)) = 1, and relax the corresponding problem by dropping the rank constraint. The reformulated problem can be expressed as
\[
\min_{\mathbf{W}_i^{(b)}, \mathbf{u}_i^{(a)}, \rho_i^{(a)}} \quad \frac{1}{K} \sum_{i=1}^{K} \sum_{b=1}^{2} \text{tr} \left\{ \mathbf{W}_i^{(b)} \right\} \\
\text{s.t.} \quad A - \frac{\sigma_i^{2}}{\rho_i^{(a)}} \geq 0, \\
B = \frac{\rho_i^{(a)}}{1 - \rho_i^{(a)}} \geq 0, \\
0 \leq \rho_i^{(a)} \leq 1, \\
\mathbf{W}_i^{(b)} \geq 0, \quad \forall (i,a), \\
\mathbf{W}_i^{(b)} \geq 0, \quad \forall (i,a),
\]  
where the variables \( A \) and \( B \) are obtained after performing some simple algebraic manipulations, and are defined as
\[
A = \frac{1}{\gamma_i^{(a)}} \left( \mathbf{u}_i^{(a)} \right)^{H} \mathbf{H}_i^{(ab)} \mathbf{W}_i^{(b)} \left( \mathbf{H}_i^{(ab)} \right)^{H} \mathbf{u}_i^{(a)} \\
- \left( \mathbf{u}_i^{(a)} \right)^{H} \Sigma_i^{(a)} \mathbf{u}_i^{(a)}, \\
B = \rho_i^{(a)} \text{tr} \left\{ \mathbf{H}_i^{(ab)} \mathbf{v}_i^{(b)} \left( \mathbf{v}_i^{(b)} \right)^{H} \mathbf{H}_i^{(ab)} \right\} \\
+ \mathbf{H}_i^{(aa)} \mathbf{v}_i^{(a)} \left( \mathbf{v}_i^{(a)} \right)^{H} \mathbf{H}_i^{(aa)} + \Sigma_i^{(a)} \right\}.
\]  
To obtain the optimal \( \mathbf{v}_i^{(b)} \), we propose an iterative alternating algorithm given on top of this page to solve problem (16). Some insightful discussion for the original problem and its solution is given in the following.

Algorithm 1: SWIPT for MIMO Full-Duplex Systems.

1. Initialize \( \mathbf{u}_i^{(a)}[n], \forall (i,a) \) and set \( n = 0 \).
2. Repeat
3. Compute \( \mathbf{v}_i^{(a)}[n+1] \) and \( \rho_i^{(a)}[n+1], \forall (i,a) \) by solving the optimal problem with fixed \( \mathbf{u}_i^{(a)}[n] \).
4. Compute \( \mathbf{u}_i^{(a)}[n+1], \forall (i,a) \) using (19) with fixed \( \mathbf{v}_i^{(a)}[n+1] \) and \( \rho_i^{(a)}[n+1] \).
5. \( n = n + 1 \).
6. Until convergence

Finding the optimal \( \mathbf{V} \): First, under fixed \( \mathbf{u}_i^{(a)} \), we drop the constraint \( \text{rank} (\mathbf{W}_i^{(b)}) = 1 \) for numerical tractability to solve for the optimal \( \mathbf{W}_i^{(b)} \) and \( \rho_i^{(a)} \). Note that, the rank of the solution \( \mathbf{W}_i^{(b)} \) can be guaranteed as rank one in general, and the randomization procedure is proposed to generate a feasible but suboptimal solution. Suppose \( \mathbf{W}^* \) is the optimal solution to the relaxed problem. Due to the relaxation, \( \text{rank}(\mathbf{W}^*) \) may not satisfy (15) in general. As a result, we adopt the randomization technique [1], [2], in which the solution \( \mathbf{W}^* \) is eigen-decomposed as \( \mathbf{W}^* = \mathbf{U}_W \mathbf{\Lambda}_W \mathbf{U}_W^{H} \), and the solution to (15) is chosen as \( \mathbf{W} = \mathbf{U}_W \mathbf{\Lambda}_W^{1/2} \mathbf{v} \mathbf{v}^{H} \mathbf{\Lambda}_W^{1/2} \mathbf{U}_W^{H} \) with \( \mathbf{N}_i \times 1 \) uniform or Gaussian distributed random vector \( \mathbf{v} \) [33], [34].

Secondly, under fixed \( \mathbf{v}_i^{(b)} \) and \( \rho_i^{(a)} \), the problem to compute the optimal \( \mathbf{u}_i^{(a)} \) boils down to a feasibility problem, which has a closed form solution, and it is given by [16], [35]
\[
\mathbf{u}_i^{(a)} = \left( \rho_i^{(a)} \Sigma_i^{(a)} + \sigma_i^{2} \mathbf{I}_{M_i} \right)^{-1} \mathbf{H}_i^{(ab)} \mathbf{v}_i^{(b)} \\
\left( \rho_i^{(a)} \Sigma_i^{(a)} + \sigma_i^{2} \mathbf{I}_{M_i} \right)^{-1} \mathbf{H}_i^{(ab)} \mathbf{v}_i^{(b)}. \tag{19}
\]

The steps of the proposed algorithm are shown in Algorithm 1.

Remark: Since the sum transmission power decreases (or stays at the same value) at each iteration, and it is lower bounded by zero, the sum transmission power will converge. But since the primal problem (15) is non-convex, global optimality is not guaranteed.

C. Complexity Analysis

In this subsection, we discuss the computational complexity of the proposed algorithm. The number of arithmetic operations required to solve a standard real-valued SDP problem
\[
\min_{\mathbf{x} \in \mathbb{R}^n} \quad c^T \mathbf{x} \\
\text{subject to} \quad \mathbf{A}_0 + \sum_{i=1}^{n} \mathbf{A}_i \mathbf{x} \geq 0, \quad \|\mathbf{x}\|_2 \leq X, \tag{21}
\]  
is given by
\[
\begin{array}{l}
\text{Algorithm 1} \\
\text{Algorithm 2}
\end{array}
where $A_i$ denotes the symmetric block-diagonal matrices with $P$ diagonal blocks of size $e_l \times e_t$, $l = 1, \ldots, P$, is upper-bounded by [36] $O(1) \left(1 + \sum_{l=1}^{P} e_l \right)^{1/2} n \left(n^2 + n \sum_{l=1}^{P} e_l^2 + \sum_{l=1}^{P} e_l^2 \right).$ (22)

The main computational complexity of Algorithm 1 arises from computing the optimal $v_i^{(a)}$ and $u_i^{(a)}$. For simplicity, let us assume same number of transmit and receive antennas at each node, i.e., $M_t = M$ and $N_i = N$, $i = 1, \ldots, K$. Accordingly the complexity analysis is given as below.

1) Computations required to calculate $v_i^{(a)}$: Since the proposed algorithm solves a SDP problem in Step 2, the number of arithmetic operations required to compute optimal $v_i$ is calculated from (22) follows. In computing $v_i$, the number of diagonal blocks $P$ is equal to $8K$. For the constraint (16b) for each node, the dimension of blocks are $e_i^{(a)} = M + 1$, $i = 1, \ldots, K$, $a \in \{1, 2\}$. For the constraint (16c), $e_i^{(a)} = 3M^2 + 1$, $i = 1, \ldots, K$, $a \in \{1, 2\}$. For the constraint (16d), and (16e), $e_i^{(a)} = 1$, and $e_i^{(a)} = N^2$, $i = 1, \ldots, K$, $a \in \{1, 2\}$, respectively. The unknown variables to be determined are of size $n = 2N^2 + 2M + 1$, where the first and second terms correspond to the real and imaginary parts of $W_i^{(a)}$ and $U_i^{(a)}$, respectively, while the third term represents the slack variable.

2) Computations required to calculate $u_i^{(a)}$: The computation of the receive beamformer is calculated from (19) as follows [37].

- Term in numerator inside the inverse: $2 \sum_{j=1}^{K} N \left(N + (1 - \frac{N+1}{2}) \right) + 2M^2$
- Term in numerator outside the inverse: $2MN - M$
- Inverse term in numerator: $M^3 + M^2 + M$
- Product of the terms in numerator (outside the inverse and the inverse): $2M^2 - M$

Accordingly, the total computational complexity to calculate the receiver matrix is in the order of $O(\phi(K^2X + KM^2(M + 5)))$, where $X = 2N \left(N + (1 - \frac{N+1}{2}) \right)$.

IV. TRANSMITTER DESIGN WITH IMPERFECT CSI

Considering a more realistic scenario, it may not be possible to obtain perfect CSI at all the IoT nodes due to, for example error of channel estimation, quantization errors, feedback delay, etc. Hence, it is necessary and important to optimize the system under imperfect CSI and design robust transceivers. In this section, we will investigate the FD MISO and MIMO interference channels again, but with the important discrepancy that the channels are now imperfectly known at the IoT nodes.

A. FD MIMO system with imperfect CSI

Considering the well-known norm-bounded error (NBE) model [38], the actual CSI from the transmitter antennas of node $b$ in the $j$th tier to the receiver antenna of node $a$ in the $i$th tier is given by $h_{ij}^{(ab)} = \tilde{H}_{ij}^{(ab)} + e_{ij}^{(ab)}$, $\forall (i, j) \in \{1, \ldots, K\}$ and $(a, b) \in \{1, 2\}$, where $\tilde{H}_{ij}^{(ab)}$ is the estimated channel vector and $e_{ij}^{(ab)}$ denotes the CSI error vector, which is bounded by its known positive constant Euclidean norm as $||e_{ij}^{(ab)}|| \leq \eta_{ij}^{(ab)}$, $(i, j) \in \{1, \ldots, K\}$ and $(a, b) \in \{1, 2\}$. (24)

In this case, the uncertainty set of $h_{ij}^{(ab)}$ can be defined as $S_{ij}^{(ab)} = \{h_{ij} = \tilde{H}_{ij}^{(ab)} + e_{ij}^{(ab)}, ||e_{ij}^{(ab)}|| \leq \eta_{ij}^{(ab)}\}$, $(i, j) \in \{1, \ldots, K\}$ and $(a, b) \in \{1, 2\}$. (25)

Accordingly, we can rewrite the optimization problem in (11) as

$$\begin{align*}
\min_{v_i^{(b)}, u_i^{(a)}} & \quad \sum_{i=1}^{K} \sum_{b=1}^{2} ||v_i^{(b)}||^2 \\
\text{s.t.} & \quad \text{SINR}_{i}^{(a)} \geq \gamma_{i}^{(a)}, \forall (i, a), \\
& \quad \mathbb{E}[h_{ij}^{(ab)}] \geq \gamma_{ij}^{(ab)}, 0 \leq \mu_{ij}^{(ab)} \leq 1, \forall (i, a), \\
& \quad \|e_{ij}^{(ab)}\|^2 \leq \eta_{ij}^{(ab)^2}, \\
& \quad (i, j) \in \{1, \ldots, K\} \text{ and } (a, b) \in \{1, 2\},
\end{align*}$$

where SINR$_{i}^{(a)}$ and EH$_{ij}^{(ab)}$ are given by (9) and (10), respectively. Now, introducing several auxiliary variables and applying the S-procedure [39] lemma, the problem for the MISO case can be expressed as (28), detailed steps of which are relegated to Appendix B. The variables $\alpha_{ii}^{(a)}, \lambda_{ij}^{(ab)}$, $c_{ij}^{(ab)}$, and $d_{ii}^{(aa)}$ are defined in (32), (33), (40), (41), (42) and (43) in Appendix A respectively. The above problem can be solved iteratively by using the standard CVX toolbox, a package in Matlab for specifying and solving convex programs [40], [41].

B. FD MIMO system with imperfect CSI

Similarly, for the MIMO scenario the actual CSI from the transmitter antennas of the node $b$ in the $j$th tier to the receiver antennas of the node $a$ in the $i$th tier can be expressed as $H_{ij}^{(ab)} = \tilde{H}_{ij}^{(ab)} + E_{ij}^{(ab)}$, $(i, j) \in \{1, \ldots, K\}$ and $(a, b) \in \{1, 2\}$, where $\tilde{H}_{ij}^{(ab)}$ is the estimated channel matrix and $E_{ij}^{(ab)}$ denotes the CSI error matrix, which is bounded by its known positive constant Frobenius norm as $||E_{ij}^{(ab)}|| \leq \eta_{ij}^{(ab)}$, $(i, j) \in \{1, \ldots, K\}$ and $(a, b) \in \{1, 2\}$. (30)

Now reformulating the SINR and EH constraints and introducing slack variables, the problem for the MIMO case can be expressed as (31), the lengthy proof of which is relegated to Appendix B. The variables $\alpha_{ii}^{(a)}, \lambda_{ij}^{(ab)}$, $c_{ij}^{(ab)}$, $d_{ii}^{(aa)}$, $\alpha_{ii}^{(a)}, \lambda_{ij}^{(ab)}$, $c_{ij}^{(ab)}$, and $d_{ii}^{(aa)}$ are defined in (69), (70), (71), (72), (80), (81), (82), (83) and (84) in Appendix B respectively. The optimal solutions can now be obtained via an alternating minimization approach.
Our solutions are of rank one in most cases, which means speaking, the solution provides a lower bound to the original imperfect CSI, and then distributes them to the IoT nodes.

By solving the problem (31), the matrices $W_i^{(b)}$, $\rho_i^{(a)}$, $\lambda_{ij}$, $\mu_{ab}$, $\alpha_{ii}$, $b_{ij}$, $\sigma_{ab}$, $c_{ij}$, $\rho_{aa}$, $\sigma_{ac}$, $\sigma_{ac}$, $\sigma_{ac}$ are of rank one in most cases, which means speaking, the solution provides a lower bound to the original imperfect CSI, and then distributes them to the IoT nodes.

The estimation of CSI matrices follows a similar strategy to that of traditional systems, as the IoT nodes cooperate with the PD. This is performed via the exchange of the training sequences and feedback, and the application of usual CSI estimation methods [43].

Accordingly, from a practical implementation perspective, it is important to note the following points:

- The devices considered for EH in this paper are mainly indoor devices, where the variation in channel is minimum. So once acquired, the channel can be estimated later with minimum error and less complicated signal processing.
- Devices such as smart watches, heart rate monitors, fitness trackers, etc., are usually required to be connected to a parent smart phone through Bluetooth LE. These low powered devices are not required to do any complex processing to acquire the CSI, which will be the task of the more capable smart phones. Once acquired, the smart phones can transmit the information to the wearable devices.
- Devices such as Nest thermostat, Google home, Microsoft Hololens, Amazon Echo, Echo Show, etc., are usually connected to a central WiFi device. Centralized algorithms can be processed at the central device, which

\[
\min_{W_i^{(b)}, \rho_i^{(a)}, \lambda_{ij}, \mu_{ab}, \alpha_{ii}, b_{ij}, \sigma_{ab}, c_{ij}, \rho_{aa}, \sigma_{ac}, \sigma_{ac}} \sum_{i=1}^{K} \sum_{b=1}^{2} \text{tr} \left\{ W_i^{(b)} \right\} 
\]

\[
\text{s.t.} \quad \begin{align*}
(28a) & \\
(28b) & \\
(28c) & \\
(28d) & \\
(28e) & \\
(28f) & \\
(28g) & \\
(28h) & \\
\end{align*}
\]

\[
\min_{W_i^{(b)}, \rho_i^{(a)}, \lambda_{ij}, \mu_{ab}, \alpha_{ii}, b_{ij}, \sigma_{ab}, c_{ij}, \rho_{aa}, \sigma_{ac}, \sigma_{ac}} \sum_{i=1}^{K} \sum_{b=1}^{2} \text{tr} \left\{ W_i^{(b)} \right\} 
\]

\[
\text{s.t.} \quad \begin{align*}
(31a) & \\
(31b) & \\
(31c) & \\
(31d) & \\
(31e) & \\
(31f) & \\
(31g) & \\
(31h) & \\
(31i) & \\
\end{align*}
\]

**Remark:** By solving the problem (31), the matrices $W_i^{(b)}$ are not guaranteed to be of rank one mathematically. Generally speaking, the solution provides a lower bound to the original problem. As we mentioned before, it is worth noting that our solutions are of rank one in most cases, which means the principal eigenvector $\lambda^{(b)}$ of $W_i^{(b)}$ is the optimal solution to the original problem. Otherwise, as explained before randomization procedure is proposed to generate a feasible but suboptimal solution [33], [34], [42].

### C. CSI Acquisition

In this paper, we consider the IoT nodes to be low powered devices. These devices can range from smart wearables to smart home appliances, which may use Bluetooth 4.0 LE/5.0 LE, IEEE 802.11n, IEEE 802.11ac, etc., along with other future communication technologies such as mmWave transmission.

We assume that the IoT devices are connected to a parent device (PD), such as a smartphone with high end signal processing capabilities. The PD has the knowledge of the nominal channels and the radius of uncertainty regions. We undertake a centralized approach where the PD collects all channel matrices, computes the beamforming matrices based on the imperfect CSI, and then distributes them to the IoT nodes.

The devices considered for EH in this paper are mainly indoor devices, where the variation in channel is minimum. So once acquired, the channel can be estimated later with minimum error and less complicated signal processing.
V. NUMERICAL RESULTS

In this section, we numerically investigate the SWIPT optimization problem for FD MISO and MIMO interference channels involving IoT nodes as a function of SINR constraints and inter-user interference power. Accordingly, we set the number of transmit and receive antennas at each node as $N_t = 3$ and $M_r = 2$, $i = 1, \ldots, K$. For simplicity, the EH and SINR thresholds are assumed to be equal\(^5\) for all receivers, i.e., $\delta = \delta_i^{(a)}$, $\gamma = \gamma_i^{(a)}$, $\forall (i, a)$, respectively. Unless otherwise stated, the parameters used for the simulation are: $\kappa = \beta = -40$ dB, $\xi_i^{(a)} = 0.5$, $\sigma_i{\nu_i\nu_i}{^{2}} = -70$ dBm, $\forall (i, a)$, and $\sigma_i^{2} = -50$ dBm. Iteration method’s performance may rely on the initialization state. As a result, it is important to select good initialization points to achieve a suboptimal solution with a good performance. While various initialization techniques, such as random initialization, right singular matrix initialization, etc., are used in literature [44], due to the problem complexity, in this paper we use the random initialization method, which is also very common in literature [45].

The tolerance (the difference between cost function of two iterations) of the proposed iterative algorithm is set to $10^{-5}$, the maximum number of iterations is set to 50, and the results are averaged over 1000 independent channel realizations. The entries of the channel $H_{ij}^{(ac)}$, $\forall (i, j, a, c)$ are i.i.d. zero-mean with variance $\sigma_{ij,ac}^{2}$. For the direct channels, i.e., $H_{ii}^{(ab)}$, $i = 1, \ldots, K$, $a \neq b$, $\sigma_{ii}^{2} = 10^{-4}$. For the inter-user interference channels, i.e., $H_{ij}^{(ac)}$, $i \neq j$, $\sigma_{ij}^{2} = \frac{10^{-4}}{n}$, with $\tau$ being the inter-user interference suppression factor and for the self-interference channel $H_{ii}^{(ab)}$, $\forall (i, a)$, $\sigma_{ii}^{2} = 10^{-5}$.

We begin by showing the evolution of the proposed algorithm, i.e., its convergence in Fig. 2. Here, the SINR threshold $= 20$ dB. The monotonic decrease of the cost function (sum power in dBm) can be verified from the figure.

After establishing the convergence of the proposed algorithm, we now show the amount of power dedicated to EH with different EH thresholds in Table I when $K = 2$ and the

---

\(^5\)In practice however, thresholds for devices will depend on their transmission power and battery capacity. For example, small devices such as wearables, might only be interested in EH, while larger devices such as smart speakers may employ EH while also transmit substantial energy for others to harvest without its quality of service (QoS) being affected.

---

Table I

<table>
<thead>
<tr>
<th>$\tau$</th>
<th>$\delta = -5$ dBm</th>
<th>$\delta = 0$ dBm</th>
<th>$\delta = 5$ dBm</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.1</td>
<td>0.0874</td>
<td>0.0853</td>
<td>0.0831</td>
</tr>
<tr>
<td>0.4</td>
<td>0.0867</td>
<td>0.0853</td>
<td>0.0831</td>
</tr>
<tr>
<td>0.7</td>
<td>0.0864</td>
<td>0.0853</td>
<td>0.0841</td>
</tr>
<tr>
<td>1.0</td>
<td>0.0864</td>
<td>0.0854</td>
<td>0.0856</td>
</tr>
</tbody>
</table>

---

SINR threshold $\gamma_i^{(a)} = 10$ dB. It is worth noting that the values in this table are the portions of total power dedicated to EH in the system. The portions increase when the EH threshold increases which is quite intuitive. However, the variance of inter-user interference channel decreases with the increase in $\tau$. However, no linear relation can be explicitly seen between the values of $\tau$ and the portions of power. Nonetheless, it can be seen that achieved power portion values are minimum when $\tau = 0.1$. In other words, when the inter-user interference is more, the amount of dedicated power required for EH is less. This result clearly shows the usefulness of inter-user interference in EH arising due to operating in FD mode. Furthermore, the optimal portion of power for each node has also been derived. For example, the optimal portion of EH for each node when $\gamma_i^{(a)} = 10$ dB and $\delta_i^{(a)} = 0$ dBm is shown in Table II.

Table II

<table>
<thead>
<tr>
<th>$\tau$</th>
<th>$a$</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.1</td>
<td>1</td>
</tr>
<tr>
<td>0.4</td>
<td>2</td>
</tr>
<tr>
<td>0.7</td>
<td>3</td>
</tr>
<tr>
<td>1.0</td>
<td>4</td>
</tr>
</tbody>
</table>

---

Next, the minimum power consumption of FD MIMO interference channel with different EH and SINR thresholds is shown in Fig. 3 when $K = 2$. It can be observed that the system power consumption increases for higher EH threshold requirements. Thus, more power is required as SINR threshold increases. For a specific EH threshold, the power consumption increases slowly with the SINR threshold. This can be attributed to the fact that the system requires more power for signal detection.

In Fig. 4, the importance of smart channel assignment, at a stage prior to the precoder/decoder design is depicted for the proposed algorithm. The value of $\tau$ represents the provided isolation among the nodes responsible for inter user

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interference. In particular, the power consumption of FD MIMO interference channel with respect to the different values of $\tau$ and EH threshold when $K = 2$ is presented. The SINR threshold is fixed in this figure at 10dB. It can be seen that the power consumption increases with $\tau$, but becomes flat later. It is worth noting that the inter-user interferences are stronger when $\tau$ is small and the system can harvest more energy from the interferences. However, the system doesn’t harvest enough energy from the interference channels when $\tau$ increases. Like before, this figure also illustrates the benefits of inter-user interference in EH.

In Fig. 5, we give the simulations for the MISO scenario. Assuming SINR threshold to be 20dB, we compare the performance of average normalized total transmitted power versus EH threshold for the case of 2, 4 and 6 nodes when $\tau = 1$. It can be seen that the average value of the total transmitted power increases monotonically with the increase of the EH threshold. Furthermore, with the increase in the number of nodes, the average normalized transmitted power also increases. It is worthwhile to note that the average normalized power increases slightly when EH threshold is less than $-15$dB. It means that the EH technique can be applied when the required energy is small, which was also applicable for the MIMO case.

Finally, Fig. 6 and 7 present the total system power consumption of imperfect FD MIMO IoT nodes. The numbers of transmit and receive antennas at each node are set as $N_i = 2$ and $M_i = 2$, $i = 1, \ldots, K$ and $K = 2$. In Fig. 6, the power consumption is much higher than the perfect CSI scenario and the difference in power consumption for different SINR thresholds are more obvious. Meanwhile, it shows that more power is needed when the EH threshold increases. Further, the bound of CSI error is verified in Fig. 6 from $\eta = \sqrt{0.1}$ to $\eta = \sqrt{0.5}$. As expected, the power consumption increases with the increase in channel uncertainty. Finally, the total power consumption is plotted with respect to $\tau$ and
different EH thresholds in Fig. 7, where the SINR threshold is 10dB and the CSI error is bounded by $\eta = \sqrt{\text{I}}$. Similar to the perfect CSI scenario, the power consumption increases with $\tau$, but becomes flat later. More power is needed owing to the uncertainty of the channel, but it also shows that the EH process is the primary beneficiary from the inter-user interference.

At this point it is worthwhile to mention that the EH threshold value chosen for the numerical analysis, satisfies the power consumption requirement of small devices, such as small low power IoT devices. Accordingly, the harvested power can definitely be considered to be utile if not sufficient to recharge their individual batteries.

**VI. CONCLUDING REMARKS**

The joint transceiver design problem for the SWIPT FD MISO/MIMO interference channels involving IoT nodes was studied under both perfect and imperfect CSI cases. An iterative alternating algorithm was proposed to design the transmit and receive filters. Meanwhile, the optimal power splitting ratio minimizing the total transmit power was derived.

The simulation results show that the EH technique works efficiently on FD MIMO IoT systems and the harvested power from EH can support charging of batteries of power consumption limited IoT devices with a specific guaranteed transmission quality.

Furthermore, in the current work for the sake of simplicity, we do not consider the dynamics of the battery to be charged. Several discretization techniques can be used to approximate the battery level after storing the harvested energy. In future, we will use steady-state probability analysis to derive the probability of having sufficient energy to charge the battery.

Also, we consider linear EH circuits in this work for analytical simplicity. While in linear EH model, the RF-to-direct current (DC) power conversion efficiency is independent of the input impedance of the EH circuit, in a non-linear end-to-end wireless power transfer circuit, this is not the case. The non-linear EH model will ensure better resource allocation for SWIPT, which will be considered in future as an extension to this work.

**APPENDIX A**

**PROBLEM REFORMULATION (IMPERFECT CSI-MISO CASE)**

Here, we show the steps for reformulating the problem (26). To begin, for the SINR constraint, we introduce three auxiliary variables as

$$a_{ab}^{(ab)} = \max_{v_{ab}^{(ab)}, e_{ab}^{(ab)}} \left( h_{ab}^{(ab)} \right)^{H} \left( \kappa (1 + \beta) \right) \times \text{diag} \left( v_{b}^{(b)} v_{b}^{(b)} \right) + \beta v_{b}^{(b)} v_{b}^{(b)} \right) \left( h_{ab}^{(ab)} \right),$$

$$b_{ab}^{(ab)} = \max_{v_{ab}^{(ab)}, e_{ab}^{(ab)}} \left( h_{ab}^{(ab)} \right)^{H} \left( \kappa (1 + \beta) \right) \times \text{diag} \left( v_{b}^{(a)} v_{b}^{(a)} \right) + \beta v_{b}^{(a)} v_{b}^{(a)} \right) \left( h_{ab}^{(ab)} \right),$$

$$c_{ac}^{(ac)} = \max_{v_{ac}^{(ac)}, e_{ac}^{(ac)}} \left( h_{ac}^{(ac)} \right)^{H} \left( \kappa (1 + \beta) \right) \times \text{diag} \left( v_{c}^{(c)} v_{c}^{(c)} \right) + \beta v_{c}^{(c)} v_{c}^{(c)} \right) \left( h_{ac}^{(ac)} \right),$$

where $a_{ab}^{(ab)}$, $b_{ab}^{(ab)}$ and $c_{ac}^{(ac)}$ are the maximum (worst cases) cross tier and self-interference. By using these three auxiliary variables, $\Sigma_{i}^{(a)}$ in eq. (7) can be rewritten as

$$\Sigma_{i}^{(a)} = a_{ab}^{(ab)} + b_{ab}^{(ab)} + \left( 1 + \beta \right) \sum_{j \neq i}^{K} \sum_{c=1}^{2} c_{ij}^{(ac)} + \sigma_{n}^{2}.$$

Then, the SINR constraint can be rewritten as

$$p_{i}^{(a)} \left( h_{ii}^{(ab)} + e_{ii}^{(ab)} \right)^{H} \left( h_{ii}^{(ab)} + e_{ii}^{(ab)} \right) - \gamma_{i}^{(a)} - \sum_{j \neq i}^{K} \gamma_{j}^{(a)} \geq 0, \quad \| e_{ii}^{(ab)} \|^{2} \leq \eta_{ii}^{2},$$

$$a_{ij}^{(ab)} \geq \left( h_{ii}^{(ab)} + e_{ii}^{(ab)} \right)^{H} \left( \kappa (1 + \beta) \right) \times \text{diag} \left( w_{ii}^{(b)} \right) + \beta w_{ii}^{(b)}$$

$$b_{ij}^{(ab)} \geq \left( h_{ii}^{(ab)} + e_{ii}^{(ab)} \right)^{H} \left( \kappa (1 + \beta) \right) \times \text{diag} \left( w_{ii}^{(a)} \right) + \beta w_{ii}^{(a)}$$

$$c_{ij}^{(ac)} \geq \left( h_{ij}^{(ac)} + e_{ij}^{(ac)} \right)^{H} \left( \kappa (1 + \beta) \right) \times \text{diag} \left( w_{ij}^{(c)} \right)$$

for $(i, j) \in \{1, \ldots, K\}$ and $(a, b) \in \{1, 2\}$.

Similarly, for EH constraint, we introduce four auxiliary variables as $(40), (41), (42)$ and (43), where $\tilde{a}_{ab}^{(ab)}, \tilde{b}_{ab}^{(ab)}, \tilde{c}_{ac}^{(ac)}$ and $\tilde{d}_{ia}^{(ia)}$ denote the minimum (worst cases) available power for...
EH from all the nodes. The covariance matrix in EH can be rewritten as

$$\Sigma_i^{(a)} = \tilde{a}_{i}^{ab} + \tilde{b}_{i}^{ab} + (1 + \beta) \left( \sum_{j=1}^{K} \sum_{c=1}^{2} \tilde{c}_{ij}^{ac} + \sigma_n^2 \right).$$ (44)

Then, the EH constraint can be rewritten as

$$\xi_i^{(a)} \left( 1 - \rho_i^{(a)} \right) \left( \tilde{h}_{i}^{ab} + e_i^{ab} \right)^H W_i^{(b)} \left( \tilde{h}_{i}^{ab} + e_i^{ab} \right)$$

$$+ \tilde{a}_{i}^{ab} \leq \left( \tilde{h}_{i}^{ab} + e_i^{ab} \right)^H \left( (1 + \beta) \diag(W_i^{(b)}) + \beta W_i^{(b)} \right) \left( \tilde{h}_{i}^{ab} + e_i^{ab} \right),$$

$$+ \beta W_i^{(b)} \left( \tilde{h}_{i}^{ab} + e_i^{ab} \right), \quad \|e_i^{ab}\|^2 \leq \eta_i^{ab2},$$

$$\tilde{b}_{i}^{ac} \leq \left( \tilde{h}_{i}^{ac} + e_i^{ac} \right)^H \left( (1 + \beta) \diag(W_i^{(c)}) + \beta W_i^{(c)} \right) \left( \tilde{h}_{i}^{ac} + e_i^{ac} \right),$$

$$+ \beta W_i^{(c)} \left( \tilde{h}_{i}^{ac} + e_i^{ac} \right), \quad \|e_i^{ac}\|^2 \leq \eta_i^{ac2},$$

$$\tilde{c}_{ij}^{ac} \leq \left( \tilde{h}_{j}^{ac} + e_j^{ac} \right)^H \left( W_j^{(c)} + \kappa \diag(W_j^{(c)}) \right)$$

$$\left( \tilde{h}_{j}^{ac} + e_j^{ac} \right), \quad \|e_j^{ac}\|^2 \leq \eta_i^{ac2},$$

$$\tilde{d}_{ij}^{ac} \leq \left( \tilde{h}_{j}^{ac} + e_j^{ac} \right)^H \left( W_j^{(c)} + \kappa \diag(W_j^{(c)}) \right) \left( \tilde{h}_{j}^{ac} + e_j^{ac} \right), \quad \|e_j^{ac}\|^2 \leq \eta_i^{ac2},$$

for $(i, j) \in \{1, \ldots, K\}$ and $(a, b) \in \{1, 2\}$.

However, this problem is still computationally intractable, because it involves an infinite number of constraints, which have to be reformulated into finite convex constraints. By applying the S-procedure [39], the SINR constraints in (36), (37), (38) and (39) can be reformulated to finite convex constraints which are equivalent to (50), (51), (52) and (53), where

$$F_1 = \kappa \left( 1 + \beta \right) \diag(W_i^{(b)}) + \beta W_i^{(b)},$$

$$F_2 = \kappa \left( 1 + \beta \right) \diag(W_i^{(a)}) + \beta W_i^{(a)},$$

$$F_3 = W_j^{(c)} + \kappa \diag(W_j^{(c)}),$$

Meanwhile, the EH constraints in (45), (46), (47) and (49) can be reformulated to finite convex constraints which are equivalent to (57), (58), (59), (60) and (61).

Accordingly, after some simple mathematical manipulations, we obtain (28).

**APPENDIX B**

**PROBLEM REFORMULATION (IMPERFECT CSI-MIMO CASE)**

Here, we show the steps for reformulating the problem (31). To begin, the SINR constraint can be rewritten as (62).

Then, the SINR constraint of this MIMO scenario can be reformulated as (63), (64), (65), (66), (67) and (68), where

$$\Sigma_i^{(a)} \triangleq \kappa \left( a_{i}^{ab} + b_{i}^{ac} \right) + \sum_{j \neq i}^{K} \sum_{c=1}^{2} c_{ij}^{ac} + \sum_{j=1}^{K} \sum_{c=1}^{2} \beta d_{ij}^{ac}$$

$$+ (u_i^{a})^H \sigma_n^2 \mathbf{I} u_i^{a},$$

$$V_{S1} \triangleq \min_{\|E_i^{(a)}\| \leq \eta_i^{ab}} \frac{1}{\gamma_i^{(a)}} \left( u_i^{(a)} \right)^H \left( H_{i}^{(ab)} + E_i^{(ab)} \right)$$

$$\times W_i^{(c)} \left( H_{i}^{(ab)} + E_i^{(ab)} \right)^H u_i^{(a)},$$

$$F_4 = \left( W_j^{(c)} + \kappa \diag(W_j^{(c)}) \right),$$

$$a_{i}^{ab} \triangleq \max_{\|E_i^{(ab)}\| \leq \eta_i^{ab}} \left( u_i^{a} \right)^H H_{i}^{(ab)} \diag(W_i^{(b)}) \left( H_{i}^{(ab)} \right)^H u_i^{a},$$

$$b_{i}^{ac} \triangleq \max_{\|E_i^{(ac)}\| \leq \eta_i^{ac}} \left( u_i^{c} \right)^H H_{i}^{(ac)} F_4 \left(H_{i}^{(ac)} \right)^H u_i^{c},$$

$$c_{ij}^{ac} \triangleq \max_{\|E_j^{(ac)}\| \leq \eta_j^{ac}} \left( u_j^{c} \right)^H \left( H_{j}^{(ac)} \right) F_4 \left( H_{i}^{(ac)} \right)^H u_i^{c},$$

$$d_{ij}^{ac} \triangleq \max_{\|E_j^{(ac)}\| \leq \eta_j^{ac}} \left( u_j^{c} \right)^H \left( H_{j}^{(ac)} \right) F_4 \left( H_{i}^{(ac)} \right)^H u_i^{c},$$

and $\lambda_i^{ab}$ are the slack variables. Note that, the slack variables in (64) and (65) should be marked differently for simulations, which use the same $\lambda_i^{ab}$. Similarly, the EH constraint can be reformulated as (73), (74), (75), (76), (77), (78) and (79), where
\[ \begin{align*}
&\left( W^{(b)} + \lambda^{ab} I \right) H^{(ab)} W^{(b)} \left( \tilde{h}_{ii}^{(ab)} \right) H^{(b)} W^{(b)} \left( \tilde{h}_{ii}^{(ab)} \right) - \gamma_{ii}^{(a)} \rho_i^{(a)} \delta_{ii}^{(a)} - \gamma_{ii}^{(a)} \sigma_{ii}^{(a)} - \lambda^{ab} \eta_{ii}^{ab 2} \right) \succeq 0, \\
&\left( -F_1 + \lambda^{ab} I \right) H^{(ab)} F_1 \left( \tilde{h}_{ii}^{(ab)} \right) H^{(ab)} F_1 \left( \tilde{h}_{ii}^{(ab)} \right) - \lambda^{ab} \eta_{ii}^{ab 2} \right) \succeq 0, \\
&\left( -F_2 + \lambda^{aa} I \right) H^{(aa)} F_2 \left( \tilde{h}_{ii}^{(aa)} \right) H^{(aa)} F_2 \left( \tilde{h}_{ii}^{(aa)} \right) - \lambda^{aa} \eta_{ii}^{aa 2} \right) \succeq 0, \\
&\left( -F_3 + \lambda^{ac} I \right) H^{(ac)} F_3 \left( \tilde{h}_{ij}^{(ac)} \right) - \lambda^{ac} \eta_{ij}^{ac 2} \right) \succeq 0, \\
&\left( \tilde{h}_{ii}^{(ab)} \right)^T H^{(ab)} \left( \tilde{h}_{ii}^{(ab)} \right) + \lambda^{ab} I \left( \tilde{h}_{ii}^{(ab)} \right) H^{(ab)} \left( \tilde{h}_{ii}^{(ab)} \right) \succeq 0, \\
&\left( F_1 + \mu_i^{ab} I \right) \left( \tilde{h}_{ii}^{(ab)} \right)^T H^{(ab)} F_1 \left( \tilde{h}_{ii}^{(ab)} \right) - \lambda^{ab} \eta_{ii}^{ab 2} \right) \succeq 0, \\
&\left( F_2 + \mu_i^{aa} I \right) \left( \tilde{h}_{ii}^{(aa)} \right)^T H^{(aa)} F_2 \left( \tilde{h}_{ii}^{(aa)} \right) - \lambda^{aa} \eta_{ii}^{aa 2} \right) \succeq 0, \\
&\left( F_3 + \mu_i^{ac} I \right) \left( \tilde{h}_{ij}^{(ac)} \right)^T H^{(ac)} F_3 \left( \tilde{h}_{ij}^{(ac)} \right) - \lambda^{ac} \eta_{ij}^{ac 2} \right) \succeq 0, \\
&\left( \tilde{h}_{ii}^{(ac)} \right)^T H^{(ac)} \left( \tilde{h}_{ii}^{(ac)} \right) \succeq 0, \\
&\min_{\|E_{ij}^{(ac)}\|_F \leq \eta_{ij}^{ac 2}} \left\{ \text{tr} \left( \tilde{h}_{ij}^{(ac)} \begin{pmatrix} W_i^{(b)} & \tilde{h}_{ij}^{(ac)} \end{pmatrix} H_{ij}^{(ac)} \right) \right\} \succeq 0. \\
\end{align*} \]
\[
\begin{align*}
\left( \begin{array}{c}
\mu_i^{(a)} \\
\sigma_i \end{array} \right) & \geq 0, \\
\frac{1}{\eta_i} \left( \begin{array}{c}
u_i^{(a)} \\
\Sigma_i^{(a)} \end{array} \right) & \in V S L - \left( \begin{array}{c} \mu_i^{(a)} \\
\Sigma_i^{(a)} \end{array} \right), \\
\left( \begin{array}{c}
u_i^{(a)} \\
\Sigma_i^{(a)} \end{array} \right)^H & \left( \begin{array}{c}
u_i^{(a)} \\
\Sigma_i^{(a)} \end{array} \right) + \lambda \geq 0,
\end{align*}
\]

(63)
\[
\begin{aligned}
\begin{pmatrix}
\ell_{i}(a) (1 - \rho_{i}^{(a)}) \\
\sqrt{\delta_{i}^{(a)}}
\end{pmatrix} & \geq 0, \\
V S'2 + \hat{a}_{i}^{ab} + \tilde{\Sigma}_{i}^{(a)} & \\
\end{aligned}
\]
\( (73) \)

\[
\begin{align*}
\text{vec} \left( \tilde{H}_{ii}^{(ab)} \right)^{H} (W_{b}^{b} \otimes I) \text{vec} \left( \tilde{H}_{ii}^{(ab)} \right) - V S'2 - \mu_{ii}^{ab} & \text{vec} \left( \tilde{H}_{ii}^{(ab)} \right)^{H} (W_{b}^{b} \otimes I) \\
\text{vec} \left( \tilde{H}_{ii}^{(ab)} \right)^{H} (W_{i}^{b} \otimes I) & \geq 0,
\end{align*}
\]
\( (74) \)

\[
\begin{align*}
\text{vec} \left( \tilde{H}_{ii}^{(aa)} \right)^{H} (W_{i}^{a} \otimes I) \text{vec} \left( \tilde{H}_{ii}^{(aa)} \right) - \hat{a}_{ii}^{aa} & \text{vec} \left( \tilde{H}_{ii}^{(aa)} \right)^{H} (W_{a}^{a} \otimes I) \\
\text{vec} \left( \tilde{H}_{ii}^{(aa)} \right)^{H} (W_{i}^{a} \otimes I) + \mu_{ii}^{aa} & \geq 0,
\end{align*}
\]
\( (75) \)

\[
\begin{align*}
\text{vec} \left( \tilde{H}_{ii}^{(ab)} \right)^{H} (\text{diag}(W_{b}^{b}) \otimes I) \text{vec} \left( \tilde{H}_{ii}^{(ab)} \right) - \hat{a}_{ii}^{ab} - \mu_{ii}^{ab} & \text{vec} \left( \tilde{H}_{ii}^{(ab)} \right)^{H} (\text{diag}(W_{b}^{b}) \otimes I) \\
\text{vec} \left( \tilde{H}_{ii}^{(ab)} \right)^{H} (\text{diag}(W_{i}^{b}) \otimes I) & \geq 0,
\end{align*}
\]
\( (76) \)

\[
\begin{align*}
\text{vec} \left( \hat{H}_{i}^{(aa)} \right)^{H} (\text{diag}(W_{a}^{a}) \otimes I) \text{vec} \left( \hat{H}_{ii}^{(aa)} \right) - \hat{a}_{ii}^{aa} & \text{vec} \left( \hat{H}_{ii}^{(aa)} \right)^{H} (\text{diag}(W_{a}^{a}) \otimes I) \\
\text{vec} \left( \hat{H}_{i}^{(aa)} \right)^{H} (\text{diag}(W_{i}^{a}) \otimes I) & \geq 0,
\end{align*}
\]
\( (77) \)

\[
\begin{align*}
\text{vec} \left( \tilde{H}_{ij}^{(ac)} \right)^{H} (F_{4} \otimes I) \text{vec} \left( \tilde{H}_{ij}^{(ac)} \right) - \hat{c}_{ij}^{ac} & \text{vec} \left( \tilde{H}_{ij}^{(ac)} \right)^{H} (F_{4} \otimes I) \\
\text{vec} \left( \tilde{H}_{ij}^{(ac)} \right)^{H} (F_{4} \otimes I) & \geq 0,
\end{align*}
\]
\( (78) \)

\[
\begin{align*}
\text{vec} \left( \tilde{H}_{ij}^{(ac)} \right)^{H} (W_{c}^{c} \otimes I) \text{vec} \left( \tilde{H}_{ij}^{(ac)} \right) - \hat{c}_{ij}^{ac} & \text{vec} \left( \tilde{H}_{ij}^{(ac)} \right)^{H} (W_{c}^{c} \otimes I) \\
\text{vec} \left( \tilde{H}_{ij}^{(ac)} \right)^{H} (W_{c}^{c} \otimes I) & \geq 0,
\end{align*}
\]
\( (79) \)
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